

FIG. 1 is a perspective view of a first embodiment of the device. It shows a rectangular base 2 with a central cylindrical component 3. A top plate 7 is hinged to the base. A circular component 6 is shown separately. A coordinate system (X, Y, Z) is shown at the bottom right with angles α and β .

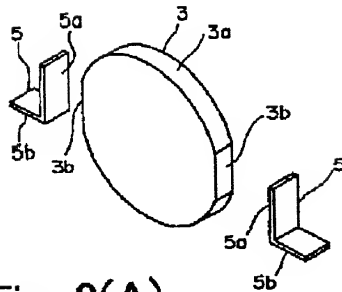


Fig. 2(A)

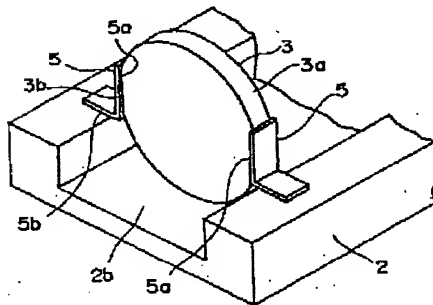


Fig. 2(B)

Fig. 3(A)

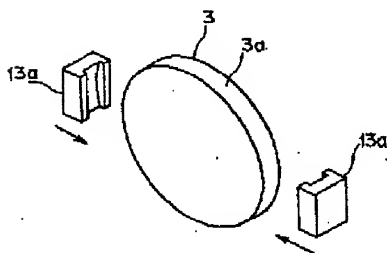
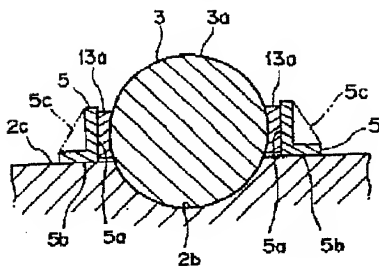


Fig. 3(B)

Fig. 4(A)

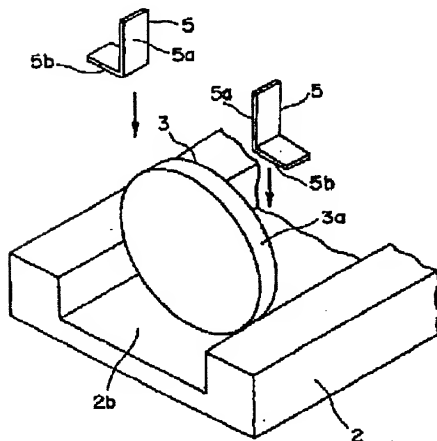


Fig. 4(B)

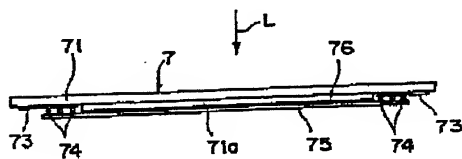
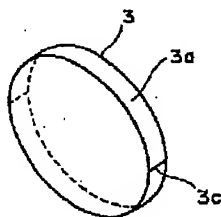


Fig. 5

Fig. 6

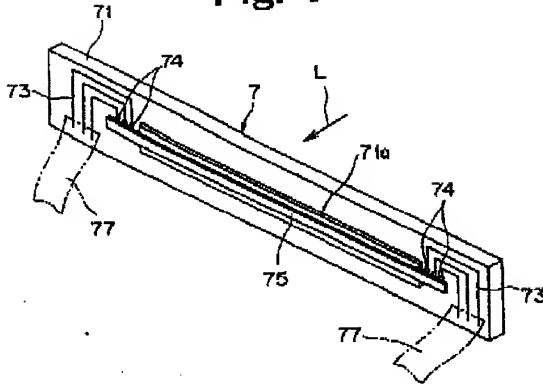


Fig. 7

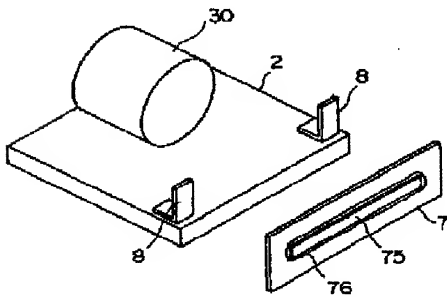
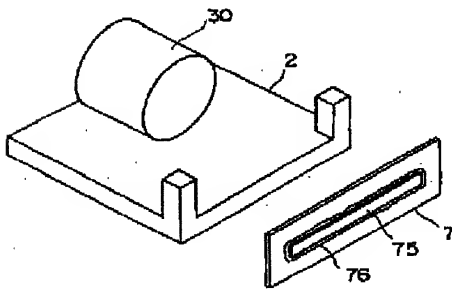


Fig. 8

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Fig. 9(A)

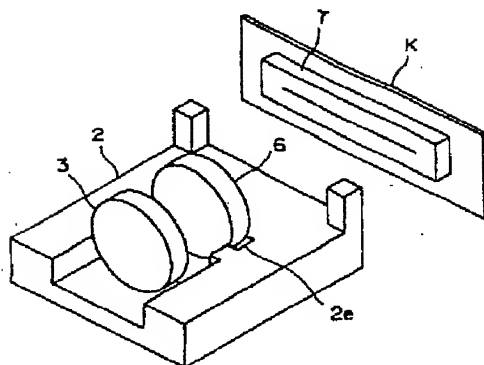
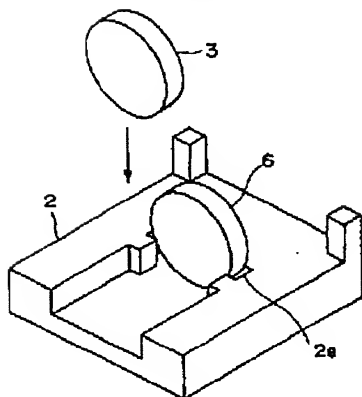


Fig. 9(B)

Fig. 10(A)

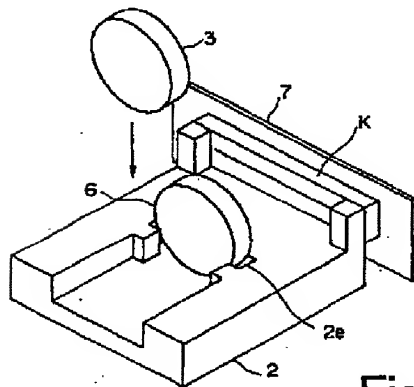
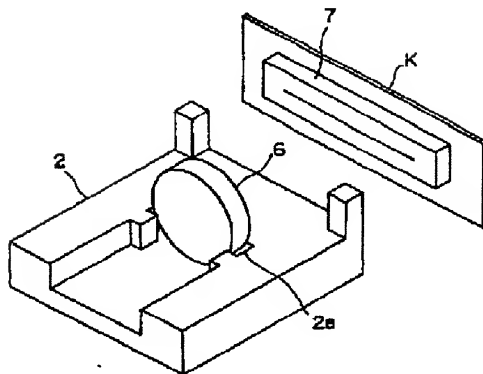


Fig. 10(B)

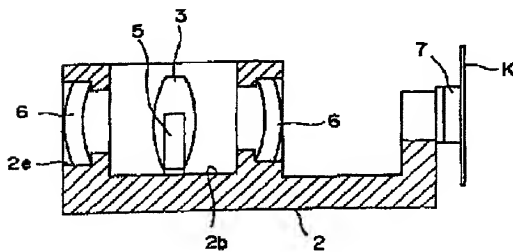


Fig. 11

Fig. 12

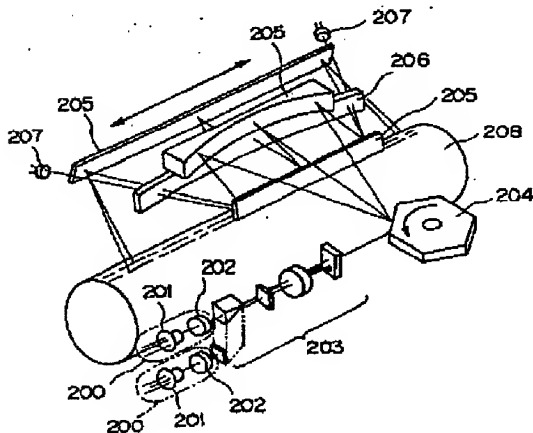
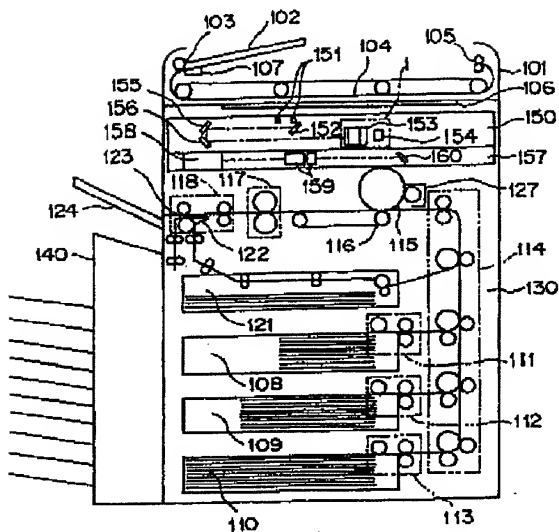


Fig. 13

Fig. 14

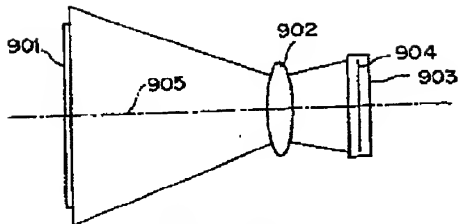


Fig. 15

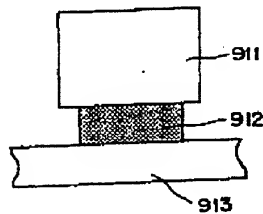
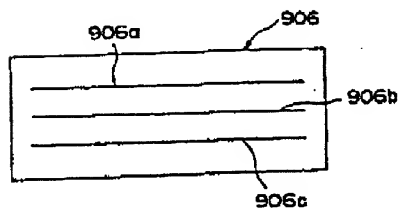


Fig. 16(A)

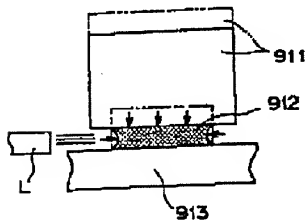


Fig. 16(B)

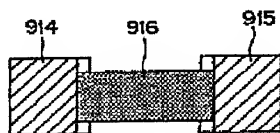


Fig. 17(B)